

University of Illinois at Urbana-Champaign
 Department of Electrical and Computer Engineering

ECE 310: Digital Signal Processing I
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Problem Set 4
 Summer 2011

Reading: Chapter 5: Sections 5.10-5.14, Chapter 8: Frequency response of LSI systems

Problem 1

Determine whether each of the following represents a BIBO stable system:

1. $H(z) = \frac{z-7}{z^2+1/9}$, causal
2. $H(z) = \frac{z-7}{z^2+1/9}$, anticausal
3. $H(z) = \frac{z}{(z-0.7)(z^2+z+1)}$, $h[n]$ is two-sided
4. $H(z) = \frac{z+1}{z-1}$, causal
5. $H(z) = \frac{z-1}{z^2+j}$, causal

For each case in which the system is determined to be unstable, find a bounded real-valued input that will produce an unbounded output.

Problem 2

For the block diagram shown in Fig. 1:

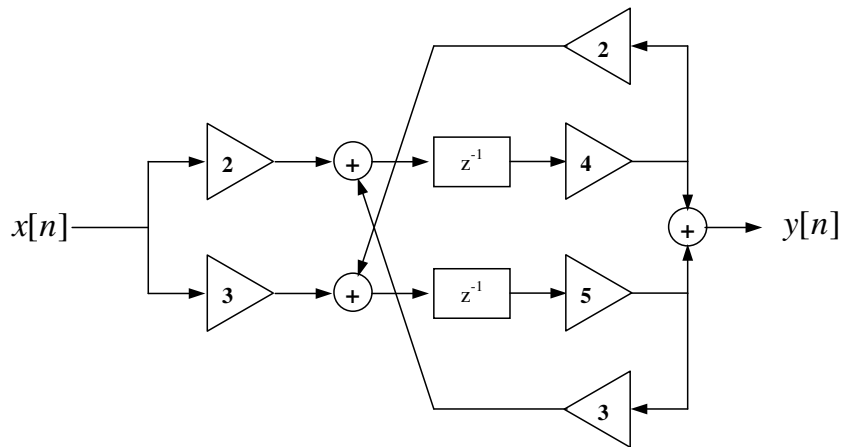


Figure 1: System for Problem 2

- a. write down the difference equation.

- b. draw the block-diagram of a direct-form II architecture that implements the same function as the block diagram shown above.

For each case in which the system is determined to be unstable, find a real-valued input that will produce an unbounded output.

Problem 3

For the difference equation $0 = 2y[n + 2] - 2y[n] + 4x[n + 2] + 2x[n + 1]$,

- Put the difference equation in standard causal form $y[n] = \dots$
- Draw a block diagram (i.e., flow diagram, or digital filter structure) implementing this difference equation.
- For the input $x[n] = \delta[n]$ and the system at rest (i.e., zero initial conditions), compute $y[-1]$, $y[0]$, $y[1]$, $y[2]$, and $y[3]$ by hand directly from the difference equation.
- Find the transfer function $H(z)$.
- Compute the unit pulse response, $h[n]$, via inverse z-transform. Confirm that $h[-1]$ through $h[3]$ are identical to the samples of the unit pulse response computed above via direct iteration of the difference equation.

Problem 4

An LSI system is described by the difference equation

$$y[n] = x[n] + x[n - 10]$$

- Compute and sketch its magnitude and phase response
- Determine its output to inputs
 - $x[n] = \cos \frac{\pi}{10}n + 3 \sin \left(\frac{\pi}{3}n + \frac{\pi}{10} \right)$
 - $x[n] = 10 + 5 \cos \left(\frac{2\pi}{5}n + \frac{\pi}{2} \right)$

Problem 5

Two systems with unit-pulse responses

$$h_1[n] = \frac{4}{7}(2)^{n-1}u[-n] + \frac{11}{7} \left(\frac{1}{4} \right)^{n-1} u[n - 1], \quad h_2[n] = \delta[n] - 3^{n-1}u[-n]$$

are connected in cascade. For each of the individual systems, as well as for the cascade, determine whether it is causal and/or BIBO stable.

Problem 6

The response of a real LSI system for input

$$x[n] = 3 + \cos \left(\frac{\pi}{4}n + 10^\circ \right) + \sin \left(\frac{\pi}{3}n + 25^\circ \right)$$

is

$$y[n] = 9 + 2 \sin \left(\frac{\pi}{4}n + 10^\circ \right) .$$

Determine the system response $\tilde{y}[n]$ for input

$$\tilde{x}[n] = 5 + 2 \sin \left(\frac{\pi}{4}n + 15^\circ \right) + 10 \cos \left(-\frac{\pi}{3}n + 25^\circ \right) .$$

Problem 7

The frequency response of an LSI system is

$$H_d(\omega) = \omega e^{j \sin(\omega)}, \quad |\omega| \leq \pi .$$

Determine the system output $y[n]$ for the following inputs:

- $x[n] = 5 + 10e^{j(\frac{\pi}{4}n + 45^\circ)} + j^n$
- $x[n] = 5 + 10 \cos(\frac{\pi}{4}n + 45^\circ) + j^n$.

Problem 8

The input $x[n] = 2^n (u[n] - 3u[n - 1])$ to an unknown LSI system produces output $y[n] = (3^n - 2^n)u[n]$.

- Determine the unit pulse response $h[n]$.
- Is the solution unique? What if the system is known to be unstable? What if it is causal?

Problem 9

Consider a filter with the system function

$$H(z) = b_0 \frac{(1 - e^{j\omega_0} z^{-1})(1 - e^{-j\omega_0} z^{-1})}{(1 - r e^{j\omega_0} z^{-1})(1 - r e^{-j\omega_0} z^{-1})}$$

- Sketch the pole-zero pattern.
- From the pole-zero pattern, using geometric arguments, show that for $r \approx 1$, the system is a notch filter and provide a rough sketch of its magnitude response if $\omega_0 = 60^\circ$.
- For $\omega_0 = 60^\circ$ choose b_0 so that the maximum value of $|H(\omega)|$ is 1.
- Draw a direct form II realization of the system.

Problem 10

There are three causal systems with the following difference equations labeled (1), (2), and (3):

$$\frac{3}{2}y[n] - \frac{7}{2}y[n - 1] + y[n - 2] = 2x[n] + x[n - 1] \tag{1}$$

$$4y[n] + 2y[n - 1] = x[n] - \frac{7}{12}x[n - 1] + \frac{1}{12}x[n - 2] \tag{2}$$

$$-y[n] + \frac{3}{10}y[n - 1] + \frac{1}{10}y[n - 2] = 2x[n] - 4x[n - 1] \tag{3}$$

- Find the expression for the transfer function of the all three systems, $H_1(z)$, $H_2(z)$, $H_3(z)$, and plot their pole-zero graphs, and determine whether each of them is BIBO stable or not.
- Two of these Filters are then connected in cascade, so that the cascaded system is BIBO stable. Select the two systems that will result in a BIBO stable system when connected in cascade. Find the expression for this system's transfer function, and then plot its pole-zero graph.
- Find the difference equation of the cascaded system.

Problem 11 The pole-zero plots of four causal systems labeled A, B, C, and D are plotted in Figures on the pages attached. Zeros are marked with an 'o' and poles are marked with an 'x'.

- Without finding the expressions of the transfer functions of the systems, determine which of the systems are BIBO stable.
- Find the expressions for all the transfer functions $H_A(z)$, $H_B(z)$; $H_C(z)$; and $H_D(z)$.
- Cascade the two systems B and C. Find the expression of the transfer function $H_B(z)H_C(z)$, determine whether it is BIBO stable, and find its inverse z-transform, $h_{BC}[n]$.

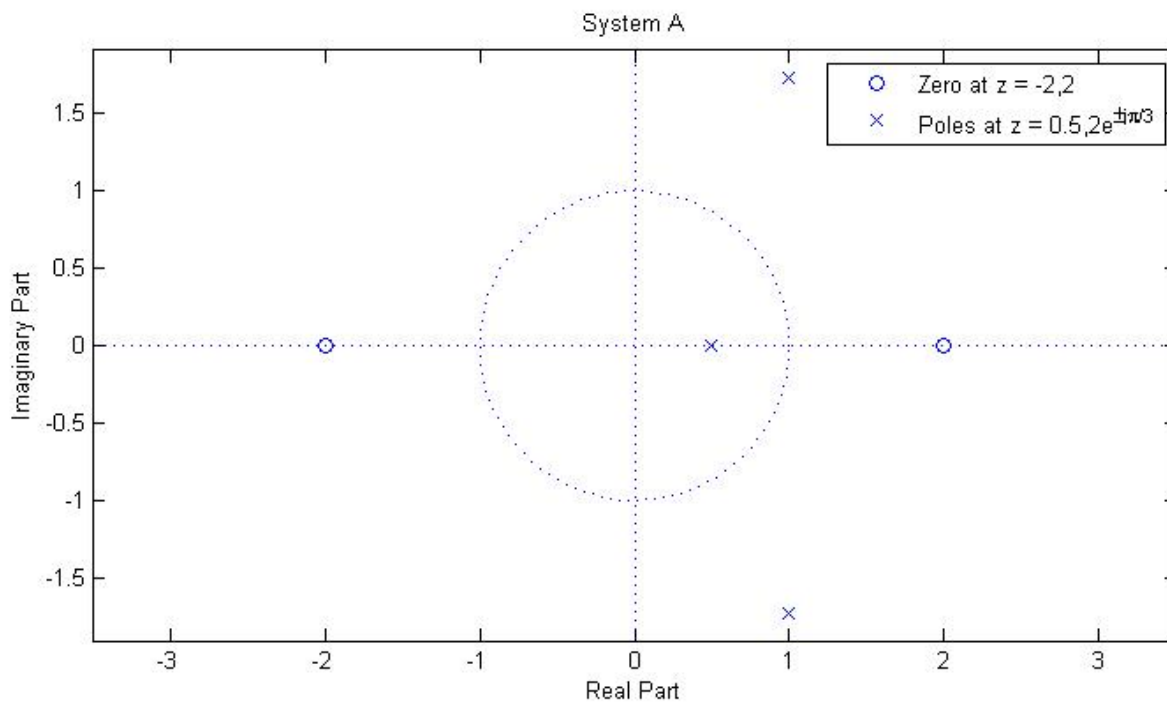


Figure 2: System A for Problem 11

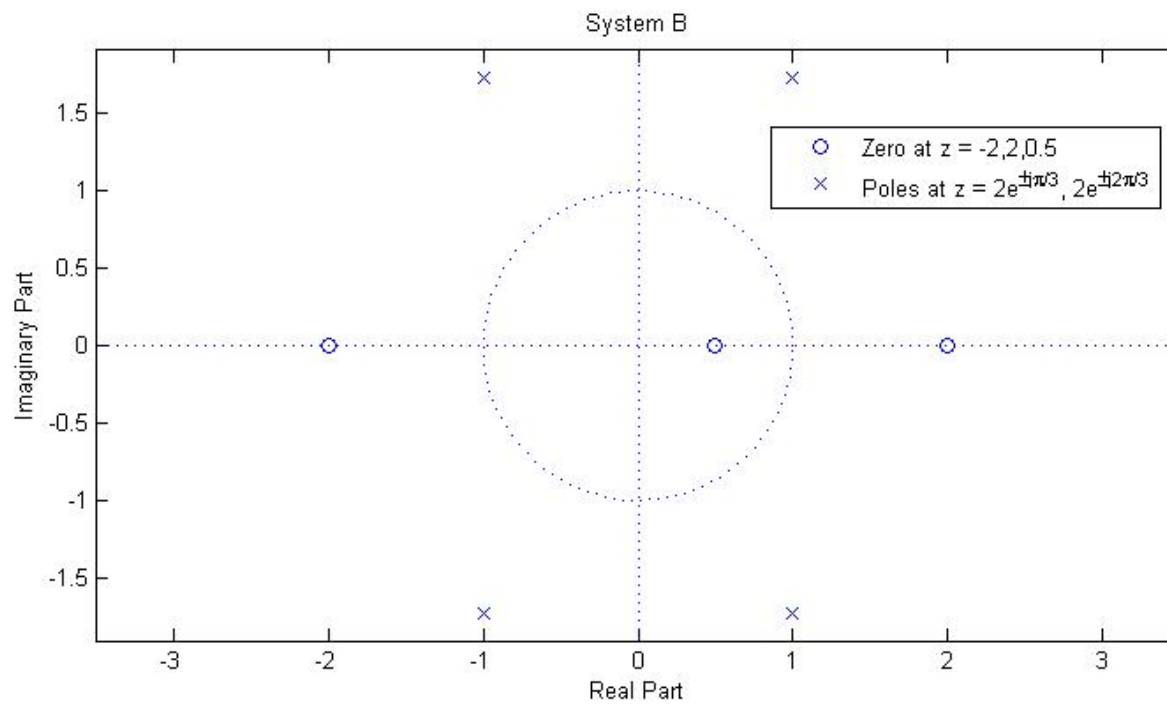


Figure 3: System B for Problem 11

- d. Cascade the two systems A and D. Find the expression of the transfer function $H_A(z)H_D(z)$, determine whether it is BIBO stable, and find its inverse z-transform, $h_{AD}[n]$.

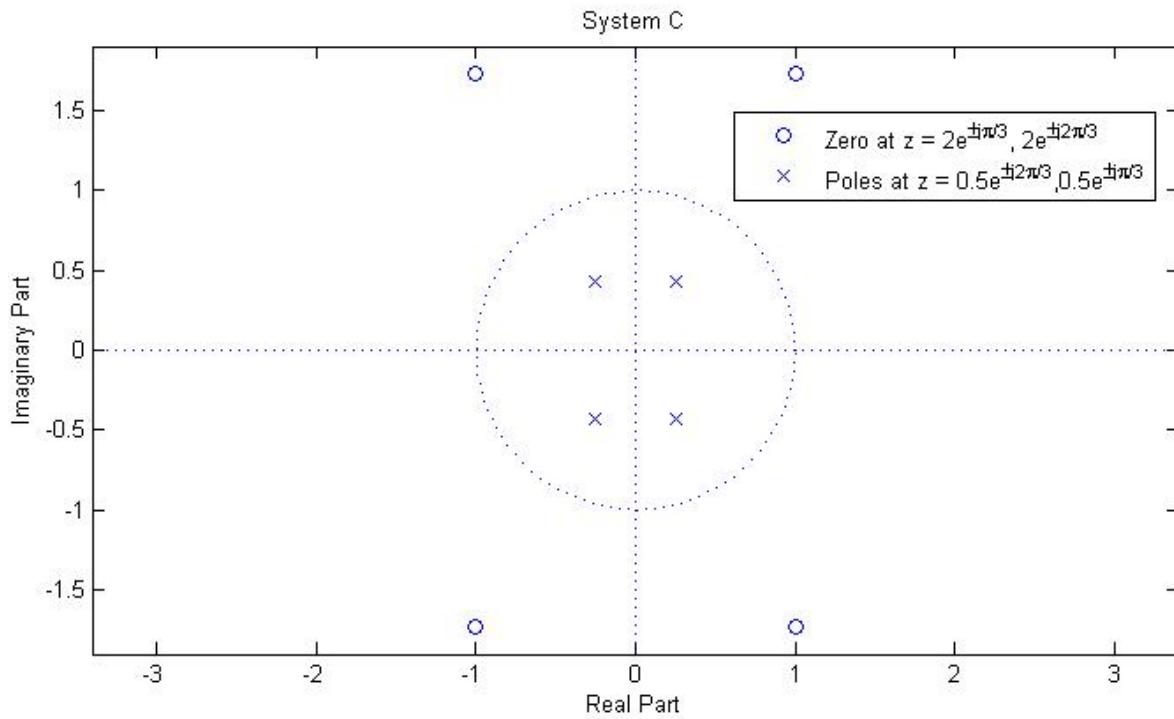


Figure 4: System C for Problem 11

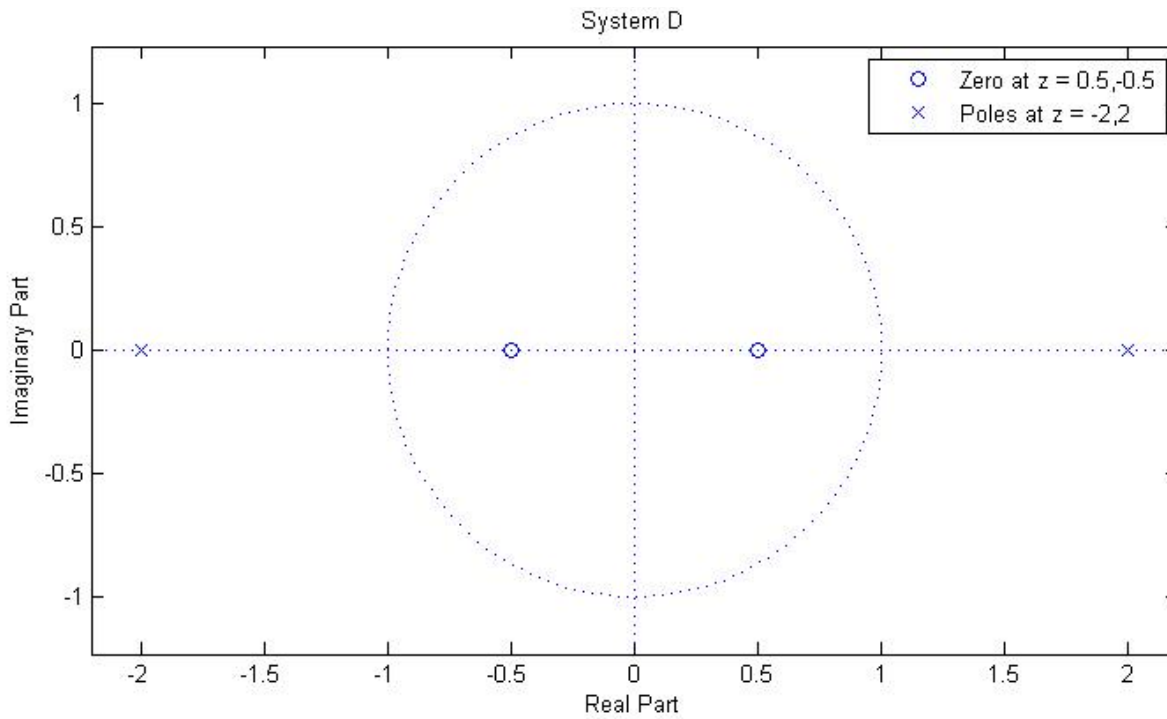


Figure 5: System D for Problem 11

***Reminder - Homework is due on 07/15/2011 at 5:00 PM - place your assignments in the ECE 410 homework drop box in Everitt Hall!**