

University of Illinois at Urbana-Champaign  
Department of Electrical and Computer Engineering

ECE 310: Digital Signal Processing I  
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Problem Set 6  
Summer 2011

Reading: Chapter 10-13: FIR Filter Design, IIR Filter Design, Digital Interpolation

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**Problem 1**

Determine the coefficients of a linear-phase FIR filter

$$y[n] = h_0x[n] + h_1x[n - 1] + h_2x[n - 2]$$

such that (i) it rejects any frequency component at  $\omega_0 = 5\pi/6$ , and (ii) its frequency response is normalized so that  $H_d(0) = 1$ .

**Problem 2**

The frequency response of a GLP filter can be expressed as  $H_d(\omega) = R(\omega)e^{j(\alpha - M\omega)}$  where  $R(\omega)$  is a real function. For each of the following filters, determine whether it is a GLP filter. If it is, find  $R(\omega)$ ,  $M$ , and  $\alpha$ , and indicate whether it is also a linear phase filter.

1.  $\{h_n\}_{n=0}^2 = \{2, 1, 1\}$
2.  $\{h_n\}_{n=0}^2 = \{1, 2, 3\}$
3.  $\{h_n\}_{n=0}^2 = \{-1, 3, 1\}$
4.  $\{h_n\}_{n=0}^4 = \{1, 1, 1, -1, -1\}$
5.  $\{h_n\}_{n=0}^2 = \{1, 0, -1\}$
6.  $\{h_n\}_{n=0}^3 = \{2, 1, 1, 2\}$

In each case, the remaining terms of the unit pulse response of the filter are zero.

**Problem 3**

- (a) Determine whether the system is FIR or IIR? If the system is FIR, sketch its  $h[n]$ .
- (b) If the system is FIR, determine whether  $h[n]$  is of even or odd length.
- (c) If the system is FIR, determine whether  $h[n]$  has even or odd symmetry, or neither.
- (d) Determine whether its  $H_d(\omega)$  has linear phase. If it does not, determine whether it has Type I or Type II generalized linear phase (GLP), or neither.

(e) The frequency response of a GLP filter can be expressed as  $H_d(\omega) = R_d(\omega) e^{j(\alpha - M\omega)}$ , where  $R_d(\omega)$  is a real function. For systems that have a GLP or linear phase, find  $R_d(\omega)$ ,  $M$ , and  $\alpha$ .

(i)  $y[n] = \frac{2}{5}x[n] - x[n-1] + x[n-2] - \frac{2}{5}x[n-3]$

(ii)  $y[n] = \frac{1}{3}x[n] + x[n-1] - \frac{3}{4}x[n-2]$

(iii)  $y[n] = x[n] + x[n-2] + x[n-4]$

**Problem 4**

Use the windowing method to design a length- $N$  low-pass, generalized linear phase FIR filter with cut-off frequency  $\pi/4$ .

1. Find an expression for the filter coefficients  $\{h_n\}_{n=0}^{N-1}$  if the rectangular window is used for the design.
2. Find an expression for the filter coefficients  $\{h_n\}_{n=0}^{N-1}$  if the Hamming window is used for the design.

**Problem 5**

Use the frequency sampling method to design a length-100 FIR high-pass filter having cutoff frequency  $3\pi/4$ .

1. Should the filter have type-1 GLP or type-2 GLP?
2. Find an expression for the filter coefficients  $\{h_n\}_{n=0}^{99}$ .

**Problem 6**

The bilinear transform is to be used with the analog prototype  $H_L(s) = \frac{s}{s+2}$  to determine the transfer function  $H(z)$  of a digital HPF with 3 dB cutoff  $\pi/3$  (i.e.,  $|H_d(\pi/3)|^2 = 0.5$ ).

1. Determine the 3 dB cutoff for the analog prototype  $\Omega_c$ .
2. Find  $H(z)$  in closed form.

**Problem 7**

For the following bilinear transformation

$$s = \frac{1 - z^{-1}}{1 + z^{-1}} \quad \text{or} \quad z = \frac{1 + s}{1 - s}$$

four points are given in the  $s$ -plane as follows: (a)  $s_1 = j$ , (b)  $s_2 = 2$ , (c)  $s_3 = -2$ , and (d)  $s_4 = 0$ . Find the corresponding  $z$ -plane points and mark their locations in the  $z$ -plane.

**Problem 8**

The transformation  $s = 2(1 - z^{-1})/(z^{-1} + 1)$  was applied to an analog prototype to design a HPF with a cutoff at  $3\pi/5$ . The width of the transition band of the resulting digital filter, from stopband edge to cutoff, is  $\pi/10$ . What is the corresponding transition bandwidth of the analog prototype?

**Problem 9** An ideal analog integrator is described by the system function  $H_L(s) = 1/s$ . A digital integrator with system function  $H(z)$  can be obtained using the bilinear transformation, that is,

$$H(z) = \frac{T}{2} \left( \frac{1 + z^{-1}}{1 - z^{-1}} \right) = H_L(s)|_{s=(2/T)(1-z^{-1})/(1+z^{-1})}$$

1. Write the difference equation for the digital integrator relating the input  $x[n]$  to the output  $y[n]$ .
2. Roughly sketch the magnitude  $|H_a(\Omega)|$  and phase  $\angle H_a(\Omega)$  of the analog integrator.

3. Show that the frequency response of the digital integrator is

$$H_d(\omega) = -j \frac{T}{2} \left( \frac{\cos(\omega/2)}{\sin(\omega/2)} \right) = -j \frac{T}{2} \cotan \left( \frac{\omega}{2} \right)$$

4. The digital integrator has a pole at  $z = 1$ . If you implement this filter on a digital computer, what restrictions might you place on the input signal sequence  $x(n)$  to avoid computational difficulties?

5.  $H_L(s)$  only has a pole. This pole was mapped by the BLT to a pole in  $H(z)$ . Where did the zero in  $H(z)$  come from?

### Problem 10

A compact disc player reproduces an audio signal having a 20 kHz bandwidth from samples collected at the rate of 44,100 samples per second. If the D/A converter uses oversampling by a factor of  $L$ , then for each value of  $L$  below, determine the maximum allowed width of the transition band of the required analog filter, such as might be used after a zero-order hold (ZOH) interpolator, for: (a)  $L = 1$ , i.e., a standard D/A; (b)  $L = 2$  and (c)  $L = 4$

### Problem 11

Consider the system illustrated in Fig. 1. The frequency response  $H_d(\omega)$  is given by,

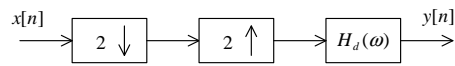


Figure 1: System for Problem 10

$$H_d(\omega) = \begin{cases} 1 & |\omega| \leq \pi/2 \\ 0 & \text{otherwise} \end{cases}$$

Find the output  $y[n]$  for the following input sequences,

(a)  $x[n] = \cos\left(\frac{\pi}{4}n\right)$

(b)  $x[n] = \cos\left(\frac{3\pi}{4}n\right)$

(c)  $x[n] = \frac{\sin\left(\frac{\pi}{8}\right)}{\pi n}$

### Problem 12

Given an input  $x[n]$ , let  $v[n]$  be the output of a sample rate expander by an integer factor  $L$ , and  $w[n]$  be the output of a sample rate compressor by an integer factor  $D$ . That is,  $w[n] = x[nD]$ , and

$$v[n] = \begin{cases} x[k] & n = Lk \\ 0 & \text{otherwise} \end{cases}$$

Given that,

$$X_d(\omega) = \begin{cases} 1 - \frac{4|\omega|}{\pi} & |\omega| \leq \pi/4 \\ 0 & \pi/4 \leq |\omega| \leq \pi \end{cases}$$

1. Sketch  $V_d(\omega)$  for  $L = 2$ .

2. Sketch  $V_d(\omega)$  for  $L = 3$ .

3. Sketch  $V_d(\omega)$  for  $D = 4$ .

**\*Reminder - Homework is due on 08/03/2011 at 5:00 PM - place your assignments in the ECE 410 homework drop box in Everitt Hall!**