# University of Illinois at Urbana-Champaign

# ECE 311: Digital Signal Processing Lab

LAB 1: SOLUTIONS

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Problem 1 Parts (a) and (b) The plots for Parts (a) and (b) are shown in Fig. 1.



Figure 1: Problem 1. Parts (a) and (b)

#### Part (c)

The real and imaginary parts are shown in Fig. 2. It can be seen from the figure that both real and imaginary parts decay exponentially.



Figure 2: Problem 1. Part (c)

Part (d) The function f(z) is shown in Fig. 3.

### Problem 2

The signal  $x_M[n]$  for M = 4, 5, 7, 10 is shown in the plots in Figs. 4, 5, 6, and 7 respectively. The fundamental period (N) for each



Figure 3: Problem 1. Part (d)

signal is,

$$N = 3(x_4[n]) N = 12(x_5[n]) N = 12(x_7[n]) N = 6(x_10[n])$$

Consider the condition for periodicity,

$$sin(\frac{2\pi M(n+k)}{N}) = sin(\frac{2\pi Mn}{N})$$
$$sin(\frac{2\pi Mn}{N} + \frac{2\pi Mk}{N}) = sin(\frac{2\pi Mn}{N} + 2\pi k_1)$$

hence we must have,

$$\frac{kM}{N} = k_1 \tag{1}$$

i.e.  $\frac{kM}{N}$  must be an integer.

We first consider M < N. Now if M and N are relatively prime then k = N satisfies the condition in (1). If M and N are not relatively prime then express M and N as a product of prime factors,

$$\frac{kM}{N} = \frac{p_1^{a_1} \cdot p_2^{a_2} \dots p_r^{a_r}}{p_1^{b_1} \cdot p_2^{b_2} \dots p_s^{b_s}}$$

canceling common factors,

$$\frac{kM}{N} = \frac{M_1}{N_1} \quad (\text{say})$$

where  $M_1$  and  $N_1$  are relatively prime. Then  $k = N_1$ . Let us take the case of M = 4 and N = 12. Now  $\frac{M}{N} = \frac{4}{12} = \frac{1}{3}$  and hence k = 3. For M = 5 and N = 12 we have k = 12. Now consider M > N, then if M is a multiple of N then k = 1. The case of M not being a multiple of N is similar to the earlier case when M, N were not relatively prime and can be handled similarly.

Problem 3

The signal  $x_k[n] = sin(\omega_k n)$  for k = 1, 2, 4, 6 is shown in the following Fig. 8. As can be seen there are 3 unique signals. This can be seen easily by writing  $sin(w_k n)$  for k = 6 as,

$$sin(\frac{2\pi 6}{5}) = sin(\frac{2\pi (5+1)}{5}) \\ = sin(2\pi + \frac{2\pi}{5}) \\ = sin(\frac{2\pi}{5})$$



Figure 4: Problem 2. The signal  $x_4[n]$ 



Figure 5: Problem 2. The signal  $x_5[n]$ 



Figure 6: Problem 2. The signal  $x_7[n]$ 

## Problem 4

The plots for the three signals,  $x_1[n], x_2[n]$ , and  $x_3[n]$  are shown in Figs. 9, 10, and 11 respectively.



Figure 7: Problem 2. The signal  $x_{10}[n]$ 



Figure 8: Problem 3. The signal  $x_k[n] = sin(w_k n)$  for k = 1, 2, 4, 6



Figure 9: Problem 4. The signal  $x_1[n] = sin(\frac{\pi n}{4})cos(\frac{\pi n}{4})$ 

It is easy to determine the period of the signals without MATLAB. Consider first the signal  $x_1[n] = sin(\frac{\pi n}{4})cos(\frac{\pi n}{4})$ ,

$$sin(\frac{\pi n}{4})cos(\frac{\pi n}{4}) = sin(\frac{\pi n}{4} + \frac{\pi n}{4}) + sin(\frac{\pi n}{4} - \frac{\pi n}{4})$$
$$= sin(\frac{\pi n}{2})$$

It can be seen that the fundamental period of  $sin(\frac{\pi n}{2})$  is N = 4.



Figure 10: Problem 4. The signal  $x_2[n] = \cos^2(\frac{\pi n}{4})$ 



Figure 11: Problem 4. The signal  $x_3[n] = sin(\frac{\pi n}{4})cos(\frac{\pi n}{8})$ 

Similarly  $\cos^2(\frac{\pi n}{4})$  can be written as,

$$\cos^2(\frac{\pi n}{4}) = \frac{1}{2} + \frac{1}{2}\cos(\frac{\pi n}{2}) = \sin(\frac{\pi n}{2})$$

The fundamental period of  $cos(\frac{\pi n}{2})$  is N = 4. Now consider  $x_3[n] = sin(\frac{\pi n}{4})cos(\frac{\pi n}{8})$ ,

$$sin(\frac{\pi n}{4})cos(\frac{\pi n}{8}) = sin(\frac{\pi n}{4} + \frac{\pi n}{8}) + sin(\frac{\pi n}{4} - \frac{\pi n}{8}) = sin(\frac{3\pi n}{8}) + sin(\frac{\pi n}{8})$$

Let us first look at  $sin(\frac{3\pi n}{8})$ . This will be periodic if

$$\sin(\frac{3\pi(n+N)}{8}) = \sin(\frac{3\pi n}{8})$$

i.e,

$$\frac{3\pi N}{8} = 2\pi k$$

Hence the fundamental period  $N_1 = 16$ . Now look at  $sin(\frac{\pi n}{8})$ . This signal is periodic if

$$\frac{\pi N}{8} = 2\pi k$$

Hence the fundamental period signal for  $sin(\frac{\pi n}{8})$  is  $N_2 = 16$ . Hence the fundamental period of  $x_3[n]$  is N = 16

#### Problem 5

The given signal x[n] and the various shifted versions of x[n] denoted by  $y_k[n]$  are shown in the Figs. 12 and 13.



Figure 12: Problem 5. The signal x[n] and its shifted versions  $y_1[n], y_2[n]$ 



Figure 13: Problem 5. The signal x[n] and its shifted versions  $y_3[n], y_4[]$